# Inference of species interaction networks with missing actors from abundance data

#### Raphaëlle Momal

Supervision: S. Robin<sup>1</sup> and C. Ambroise<sup>2</sup>

<sup>1</sup>UMR AgroParisTech / INRA MIA-Paris <sup>2</sup>LaMME, Evry

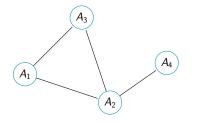
March 10th, 2020



GdR EcoStat Rennes 2020

# Statistical framework for conditional dependence

Graphical Models:



- Connected: all variables are dependant
- Markov property : G encodes the conditional independences

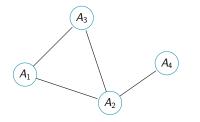
e.g.  $A_4 \perp \perp (A_1, A_3) | A_2$ 

$$p(A_1,\ldots,A_p)\propto \prod_{C\in \mathcal{C}_G}\psi_C(A_C)$$

where  $C_G$  = set of maximal cliques of G.

#### Statistical framework for conditional dependence

Graphical Models:



- Connected: all variables are dependant
- Markov property : G encodes the conditional independences

e.g. 
$$A_4 \perp\!\!\!\perp (A_1, A_3) \mid A_2$$

Here:

$$P(A) \propto \psi_1(A_1, A_2, A_3) \ \psi_2(A_2, A_4)$$

#### Gaussian Graphical Models (GGM)

$$Y = (Y_1, ..., Y_d) \sim \mathcal{N}_d(0, \Omega^{-1})$$

The factorization is straightforward:

$$p(y) \propto \prod_{j,k:\omega_{jk}\neq 0} exp(-y_j\omega_{jk}y_k/2)$$

< A >

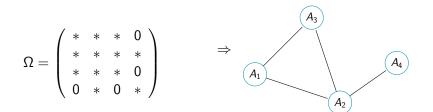
I= nac

#### Gaussian Graphical Models (GGM)

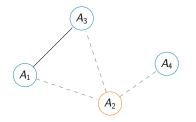
$$Y = (Y_1, ..., Y_d) \sim \mathcal{N}_d(0, \Omega^{-1})$$

The factorization is straightforward:

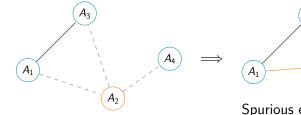
$$p(y) \propto \prod_{j,k:\omega_{jk}\neq 0} exp(-y_j\omega_{jk}y_k/2)$$



 $A_2$  is not observed:



 $A_2$  is not observed:

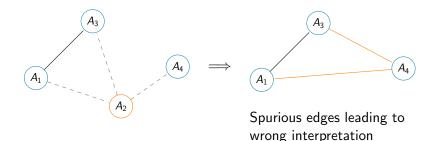


Spurious edges leading to wrong interpretation

 $A_3$ 

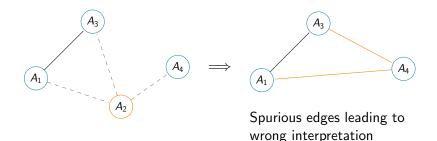
 $A_4$ 

 $A_2$  is not observed:



How to infer a missing actor in a network ?

 $A_2$  is not observed:



How to infer (a missing actor in) a network from abundance data?

#### Graphical model for abundance data

 $P\ell N$  model:

 $Y_{ij} \sim \mathcal{P}(\exp(\underbrace{o_{ij} + x_i^{\mathsf{T}} \boldsymbol{\theta}_j}_{j} + \underbrace{Z_{ij}})).$ fixed random

ELE NOR

#### Graphical model for abundance data

 $P\ell N$  model:

$$Y_{ij} \sim \mathcal{P}ig( \exp(\underbrace{o_{ij} + x_i^{\mathsf{T}} oldsymbol{ heta}_j}_{ ext{fixed}} + \underbrace{Z_{ij}}_{ ext{random}} ig)ig).$$

- Classically (Aitchison and Ho, 1989):  $\mathbf{Z}_i \sim \mathcal{N}(0, \Omega^{-1})$  iid
- Easy handling of multi-variate data, offsets and covariates (Chiquet et al., 2018)

GGM:  $\Omega$  encodes the conditional dependency structure.

#### Graphical model for abundance data

 $P\ell N$  model:

$$Y_{ij} \sim \mathcal{P} \big( \exp(\underbrace{o_{ij} + x_i^{\mathsf{T}} \boldsymbol{\theta}_j}_{\text{fixed}} + \underbrace{Z_{ij}}_{\text{random}}) \big).$$

Classically (Aitchison and Ho, 1989):  $\mathbf{Z}_i \sim \mathcal{N}(0, \Omega^{-1})$  iid

 Easy handling of multi-variate data, offsets and covariates (Chiquet et al., 2018)

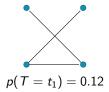
GGM:  $\Omega$  encodes the conditional dependency structure.

Momal et al. (2020): foster sparsity with a random spanning tree:

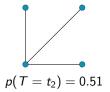
 $Z|T \sim \mathcal{N}(0, \Omega_T^{-1})$ 

Inference with an efficient variational EM algorithm.

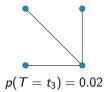
ELE NOR

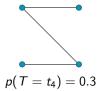


< 🗗 🕨

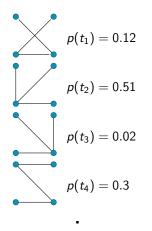


< 4 ► 1

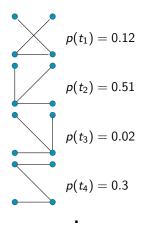




< 4 ► 1



ъ.



Edge probabilities<sup>1</sup>:



$$\mathbb{P}((j,k) \in T) = \sum_{\substack{t \in \mathcal{T} \ (j,k) \in t}} p(t)$$

<sup>1</sup>https://github.com/Rmomal/EMtree

Missing actor in network inference

GdR EcoStat Rennes 2020

#### More dimensions ?



Missing actor in network inference

GdR EcoStat Rennes 2020

March 10<sup>th</sup>, 2020 7 / 1

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

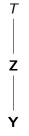
#### More dimensions ?



- Unobserved species
- Unobserved covariate ?

Gaussian case: Robin et al. (2019)

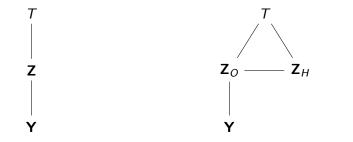
## Graphical model with missing actors



$$vBIC_0 = \mathcal{J}_0(\mathbf{Y}) - \frac{D}{2}\log(n)$$

ELE DOG

#### Graphical model with missing actors



$$vBIC_0 = \mathcal{J}_0(\mathbf{Y}) - \frac{D}{2}\log(n)$$
  $vBIC_q = \mathcal{J}_q(\mathbf{Y}) - \frac{D+2pq}{2}\log(n)$ 

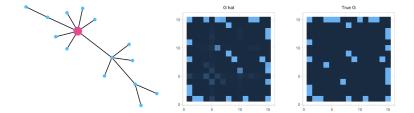
I= nac

Results on a scale-free graph /!\Work in progress /!\

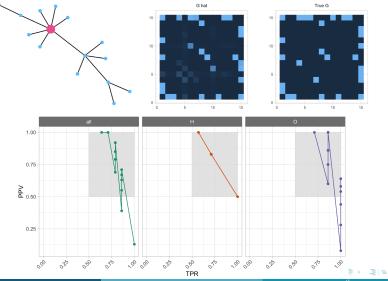
- ∢ 🗗 ▶

ELE DOG

#### Results on a scale-free graph /!\Work in progress /!\



## Results on a scale-free graph /!\Work in progress /!\



Missing actor in network inference

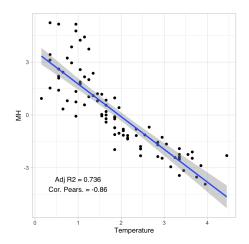
#### Barents fish data

- Abundances of 30 species in 89 sites of the Barents sea
- 4 available covariates (temperature, longitude, latitude, depth)

Selection model criteria (no covariates):

 $vBIC_0 = 4431$  vs.  $vBIC_1 = 8501$ 

#### Inference with no covariates



The inferred means of the missing actor are highly linked to the temperature

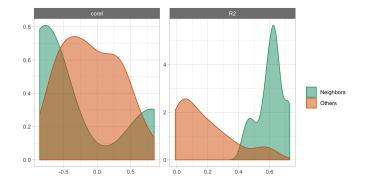
Missing actor in network inference

GdR EcoStat Rennes 2020

March 10<sup>th</sup>, 2020 11

E SQA

#### Inference with no covariates



Neighbors of the missing actor are also highly linked to the temperature

March 10<sup>th</sup>, 2020

#### In a nutshell

#### Contributions

- Probabilistic model for detecting missing actor in species interaction network inference from abundance data
- Efficient variational inference, selection model criteria
- Missing actor characterization through its means and neighborhood

#### Perspectives

- Accounting for spatial effects of ecological datasets for network inference (violation of sites independence hypothesis)
- Spatial effects as missing actors in the network ?

# Thank you!

Contact :

email raphaelle.momal@agroparistech.fr Web Rmomal.github.io Twitter @MomalRaphaelle

Currently looking for a job opportunity!

ELE NOR

#### References I

Aitchison, J. and Ho, C. (1989). The multivariate Poisson-log normal distribution. Biometrika, 76(4):643-653.

- Chiquet, J., Mariadassou, M., Robin, S., et al. (2018). Variational inference for probabilistic poisson pca. The Annals of Applied Statistics, 12(4):2674–2698.
- Momal, R., Robin, S., and Ambroise, C. (2020). Tree-based inference of species interaction networks from abundance data. Methods in Ecology and Evolution.
- Robin, G., Ambroise, C., and Robin, S. (2019). Incomplete graphical model inference via latent tree aggregation. Statistical Modelling, 19(5):545–568.